

# POD Analysis of T

M. F

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# Turbulent Pipe Flow

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9-10 Wed 03:38

## 1. Code Execut

tion and Layout

## 1.1. L

1. b7.m
2. initSpectral.m
  - reads i
3.  $\hookrightarrow$  initEigs.m
  - forms

layout

in binary files, takes eg m-fft

corrMat, finds eigenvalues

1.  $\hookrightarrow$  initPod.m

- carries out POD calculations (quadrature, multiplication)  
Hellstrom Smits 2017 for Snapshot POD)

2.  $\hookrightarrow$  timeReconstructFlow.m

- performs 2d reconstruction + plotSkmr (generates 1d ra

Layout 2

ggf between  $\alpha\Phi$ ) according to Papers (Citriniti George 2000 for Classic POD,

dial graph)

### 1.3. Importa

`pipe = Pipe();` creates a Pipe Class. As the function

1. `obj.CaseId` - stores properties like  $Re$ , rotation number  $S$ , experiment  
frequently called vectors (`rMat`  $r = 1, \dots, 0.5$ )
2. `obj.pod` - eigen data, used for calculating POD
3. `obj.solution` - computed POD modes
4. `obj.plt` - plot configuration

ant Switches

ns (above) are called, data is stored in sub-structs:

al flags such as quadrature (simpson/trapezoidal), number of gridpoints,

## 2. Equations Used

in Code Procedure

2.1. Classic P

The following equations a

$$\int_{r'} \mathbf{S}(k;m;r,r') \, \Phi^{(n)}(k;m;r')$$

$$\mathbf{S}(k;m;r,r') = \lim_{\tau \rightarrow \infty} \frac{1}{\tau} \int_0^\tau \mathbf{u}(k$$

$$\alpha^{(n)}(k;m;t) = \int_r \mathbf{u}(k;m;r,t) \Phi$$

OD Equations

re used in the above code.

$$r' \, \mathrm{d}r' = \lambda^{(n)}(k; m) \Phi^{(n)}(k; m; r)$$

$$; m; r, t) \mathbf{u}^* (k; m; r', t) \, \mathrm{d}t$$

$$\mathfrak{L}^{(n)*}(k; m; r) r \, \mathrm{d}r$$

## 2.2. Classic POD

$$\int_{r'} \underbrace{r^{1/2} S_{i,j}(r,r';m;f) r^{1/2}}_{W_{i,j}(r,r';m;f)} \\
= \underbrace{\lambda^{(n)}(m,f)}_{\hat{\lambda}^{(n)}(m;f)} \underbrace{r^{1/2} \phi_i^{(n)}(r;)}_{\hat{\phi}_i^{(n)}(r,m;f)}$$

$$\alpha_n(m;t) = \int_r \mathbf{u}(m;r,t) r$$

Equations (Fixed)

$$\underbrace{\int_0^1 \phi_j^{*(n)}(r';m;f) r'^{1/2} \mathrm{d}r'}_{\hat{\phi}_j^{\psi(i)}(r';m;f)} \\ \underbrace{\phantom{\int_0^1 \phi_j^{*(n)}(r';m;f) r'^{1/2} \mathrm{d}r'}}_{m;f)} \\ f)$$

$$.1/2\Phi_n^*(m;r)dr$$

### 2.3. Snapshot E

$$\lim_{\tau \rightarrow \infty} \frac{1}{\tau} \int_0^\tau \mathbf{u}_T(k; m; r, t)$$

$$= \Phi_T^{(n)}(k; m; r) \lambda^{(n)}(k; m$$

$$\mathbf{R}(k; m; t, t') = \int_r \mathbf{u}(k; r$$

$$\lim_{\tau \rightarrow \infty} \frac{1}{\tau} \int_0^\tau \mathbf{u}_T(k; m; r, t)$$

$$= \Phi_T^{(n)}(k; m; r) \lambda^{(n)}(k; m$$

POD Equations

$$\alpha^{(n)*}(k;m;t)dt$$

)

$$n;r,t)\mathbf{u}^*(k;m;r,t')\,r\,\mathrm{d}r$$

$$\alpha^{(n)*}(k;m;t)\,\mathrm{d}t$$

).

## 2.4. Recon

The reconstruc

$$q(\xi, t) - \bar{q}(\xi) \approx \sum_{j=1}^r a_j(t) \varphi_j(\xi)$$

$$q(r, \theta, t; x) = \bar{q}(r, \theta, t; x) +$$

Since the snapshot pod implementation is not error-free, the re

$$q(r, \theta, t; x) = \bar{q}(r, \theta, t; x) + (\text{factor}$$

nstruction

tion is given by

$\Rightarrow$

$$\sum_{n=1} \sum_{m=0} \alpha^{(n)}(m;t) \Phi^{(n)}(r;m;x)$$

construction can only be recovered by writing for factor  $\gg 0$ .

$$r\gamma) \sum_{n=1} \sum_{m=0} \alpha^{(n)}(m;t) \Phi^{(n)}(r;m;x)$$

## 2.5. Reco

In order to reconstruct in code, `caseId.fluctuation = 'off'`. The

nstruction

this is incorrect. The necessary use of (factor  $\gamma$ ) is incorrect

### 3. Der

To derive the questioned eq

$$\frac{1}{\tau} \int_0^\tau \mathbf{u}_T(k; m; r,$$

Substitute  $\mathbf{u}_T$  w

$$\frac{1}{\tau} \int_0^\tau \left( \sum_l \Phi_T^{(l)}(k; m; r) \alpha^{(l)} \right.$$

ivation

uation, consider the integral:

$$t)\alpha^{(n)*}(k;m;t)dt.$$

ith its expansion:

$$)\alpha^{(n)*}(k;m;t)\Big)\alpha^{(n)*}(k;m;t)dt.$$

Exchange the order of summation and

$$\sum_l \Phi_{\text{T}}^{(l)}(k; m; r) \left( \frac{1}{\tau} \int_0^\tau \alpha^{(l)} \right)$$

Due to the orthogonality, namely t

$$\langle a^{(n)} \alpha^{(p)} \rangle$$

all terms where  $l \neq n$  will vanish, and

$$\Phi_{\text{T}}^{(n)}(k; m; r) \left( \frac{1}{\tau} \int_0^\tau \alpha^{(n)} \right)$$

This derivation assumes the normalization of modes and their orthogonality, form that reveals the spatial structure (  $\Phi_{\text{T}}^{(n)}$  )

derivation

and integration, and apply orthogonality,

$$\int_0^T \alpha^{(l)}(k; m; t) \alpha^{(n)*}(k; m; t) dt \Bigg).$$

that  $\alpha^{(n)}$  and  $\alpha^{(p)}$  are uncorrelated

$$= \lambda^{(n)} \delta_{np}$$

and there remains only the  $l = n$  term,

$$\int_0^T \alpha^{(n)}(k; m; t) \alpha^{(n)*}(k; m; t) dt \Bigg).$$

along with the eigenvalue relationship to simplify the original integral into a sum of each mode scaled by its significance  $(\lambda^{(n)})$ .

The cross-correlation tensor  $\mathbf{R}$  is defined as  $\mathbf{R}(k; m; t, t') = \int_r \mathbf{u}(k; m; r, t) \mathbf{u}(k; m; r, t')$  tensor. The  $n$  POD m

$$\lim_{\tau \rightarrow \infty} \frac{1}{\tau} \int_0^\tau \mathbf{u}_T(k; m; r, t) \alpha^{(n)*}(k; r, t) dt$$

erivation

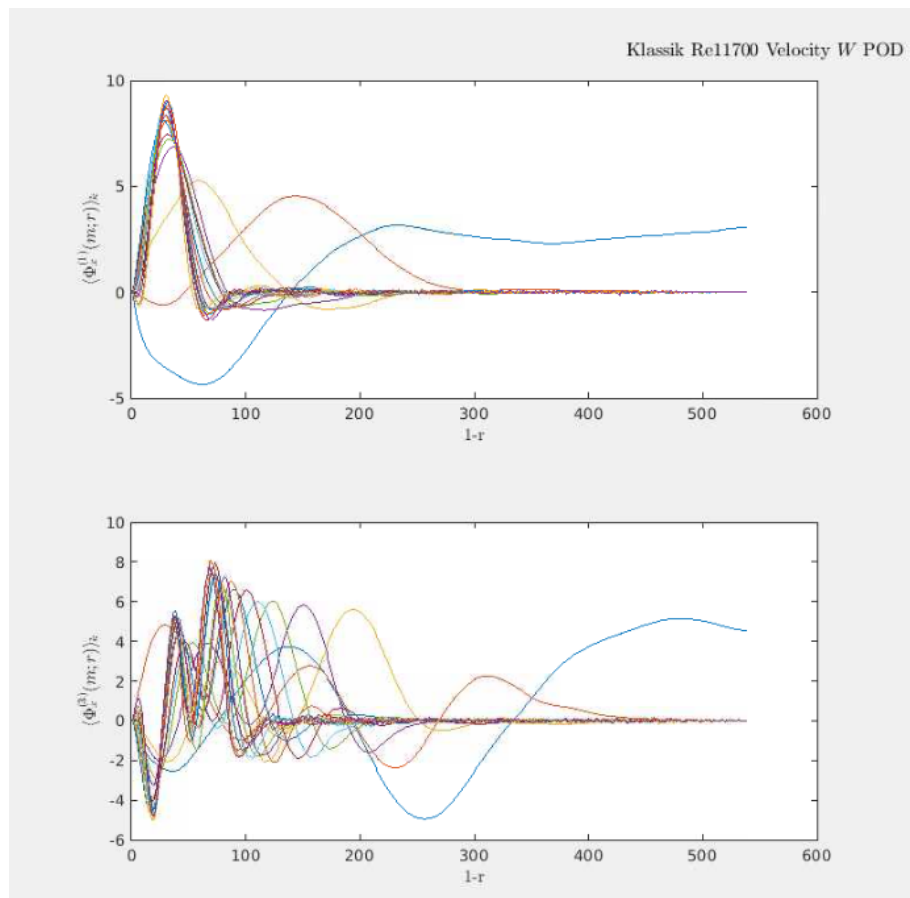
$t)\mathbf{u}^*(k;m;r,t')\,r\,\mathrm{d}r$ . This tensor is now transformed from  $[3r\times 3r']$  to a  
nodes are then constructed as,

$$n;t)\mathrm{d}t=\Phi_{\mathrm{T}}^{(n)}(k;m;r)\lambda^{(n)}(k;m).$$

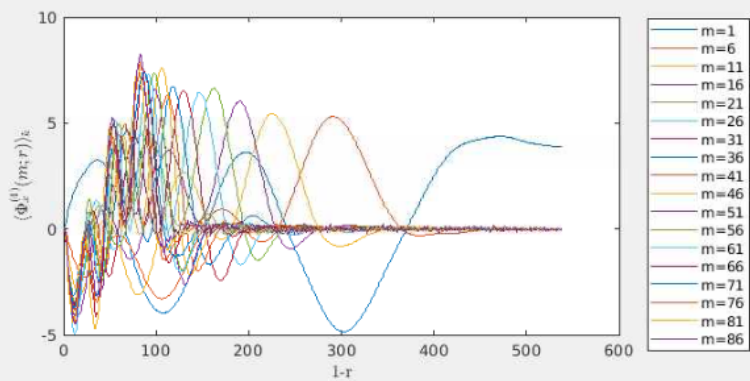
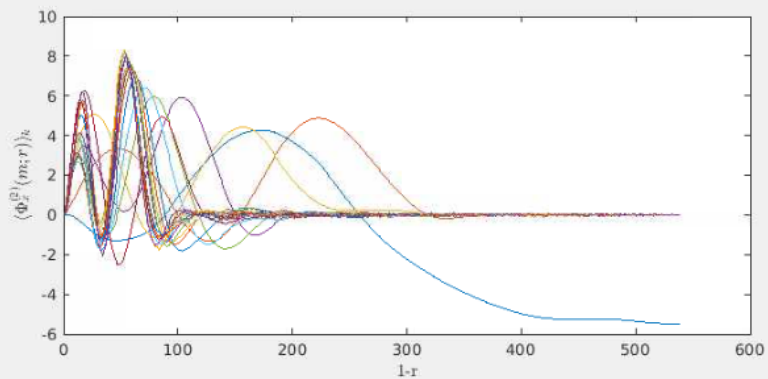
## 4. Result Comparison

on Classic/Snapshot

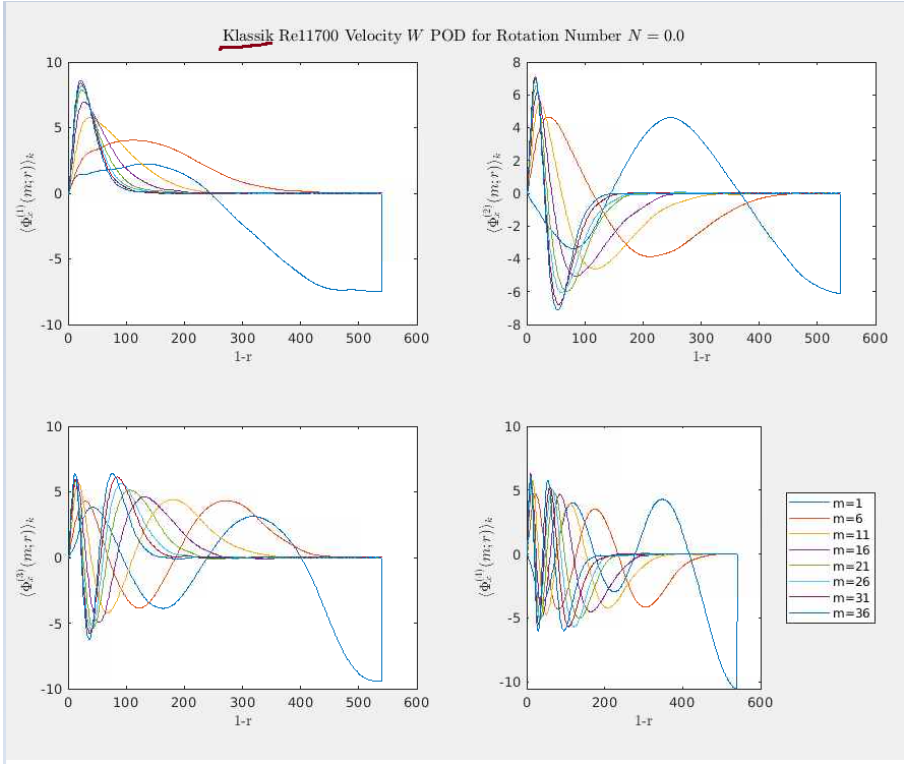
#### 4.1. Radi



for Rotation Number  $N = 3.0$

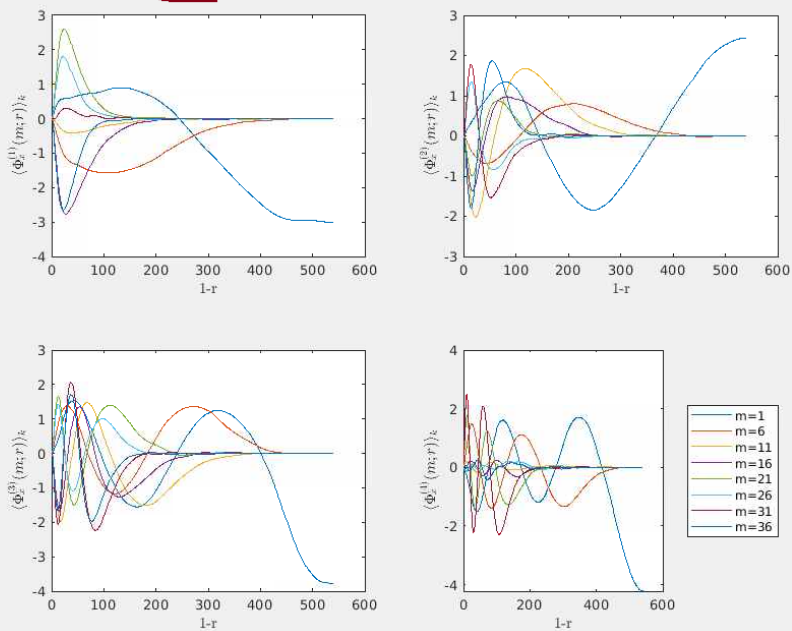


4.2. Snapshot-Cl

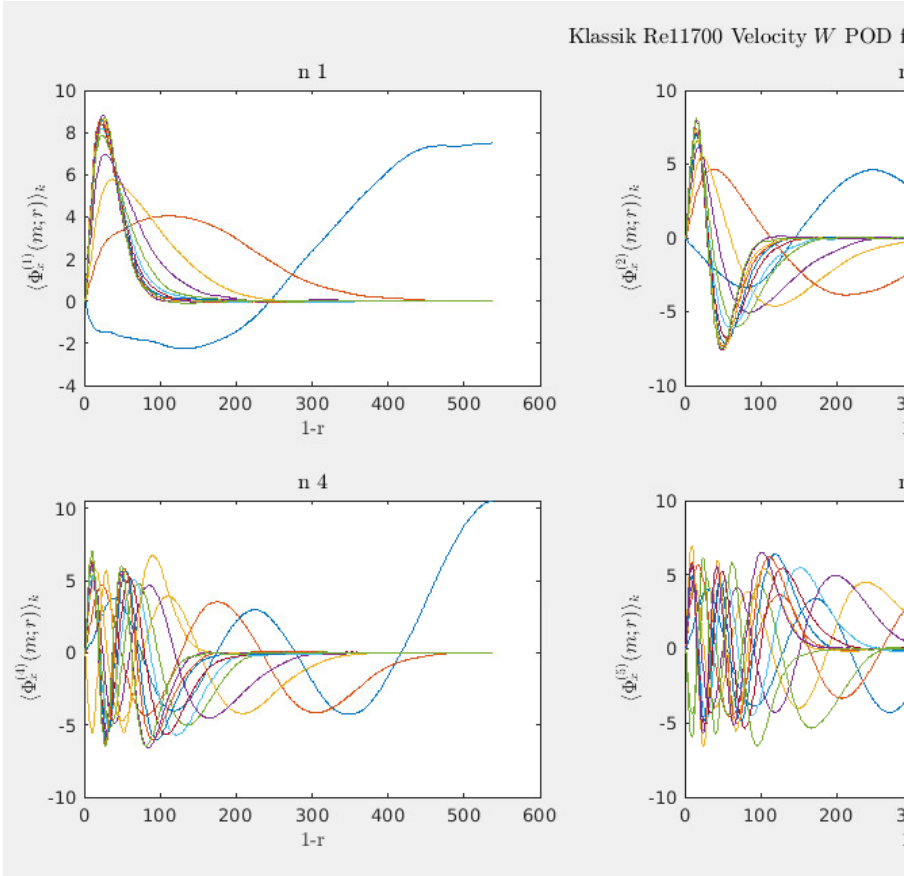


## Classic Comparison

Snapshot Rel1700 Velocity  $W$  POD for Rotation Number  $N = 0.0$



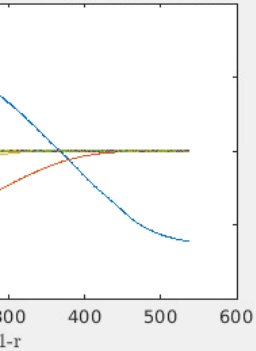
4.3. Klassik



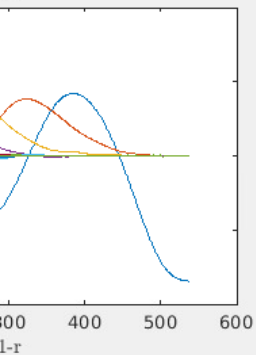
POD S=0.0

For Rotation Number  $N = 0.0$

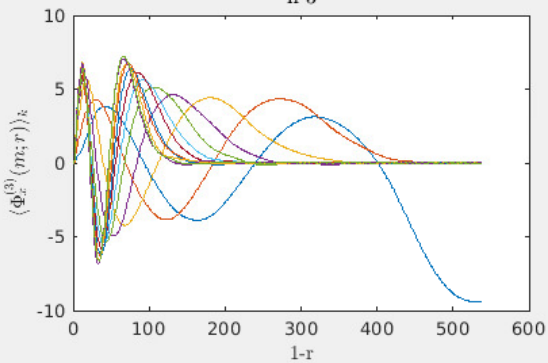
n 2



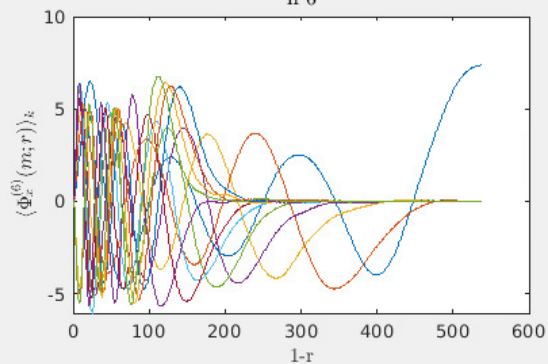
n 5



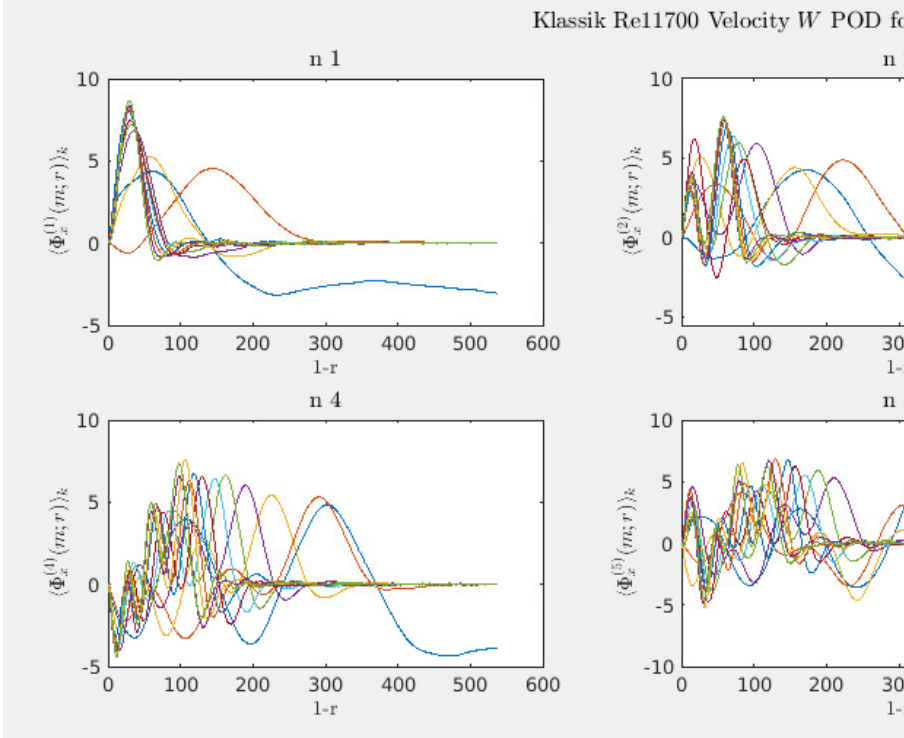
n 3



n 6

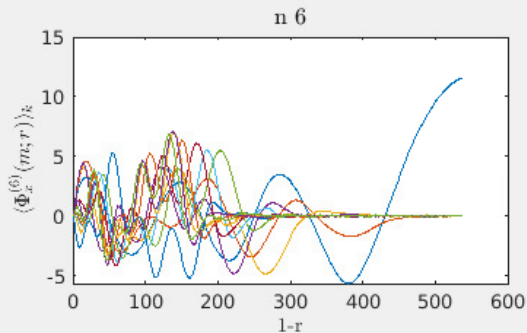
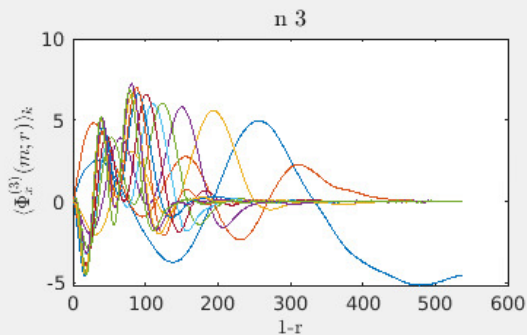
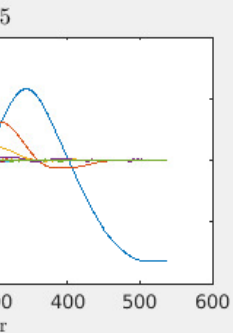
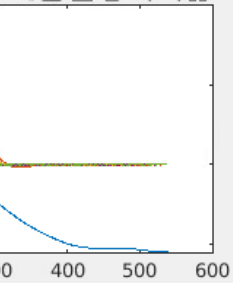


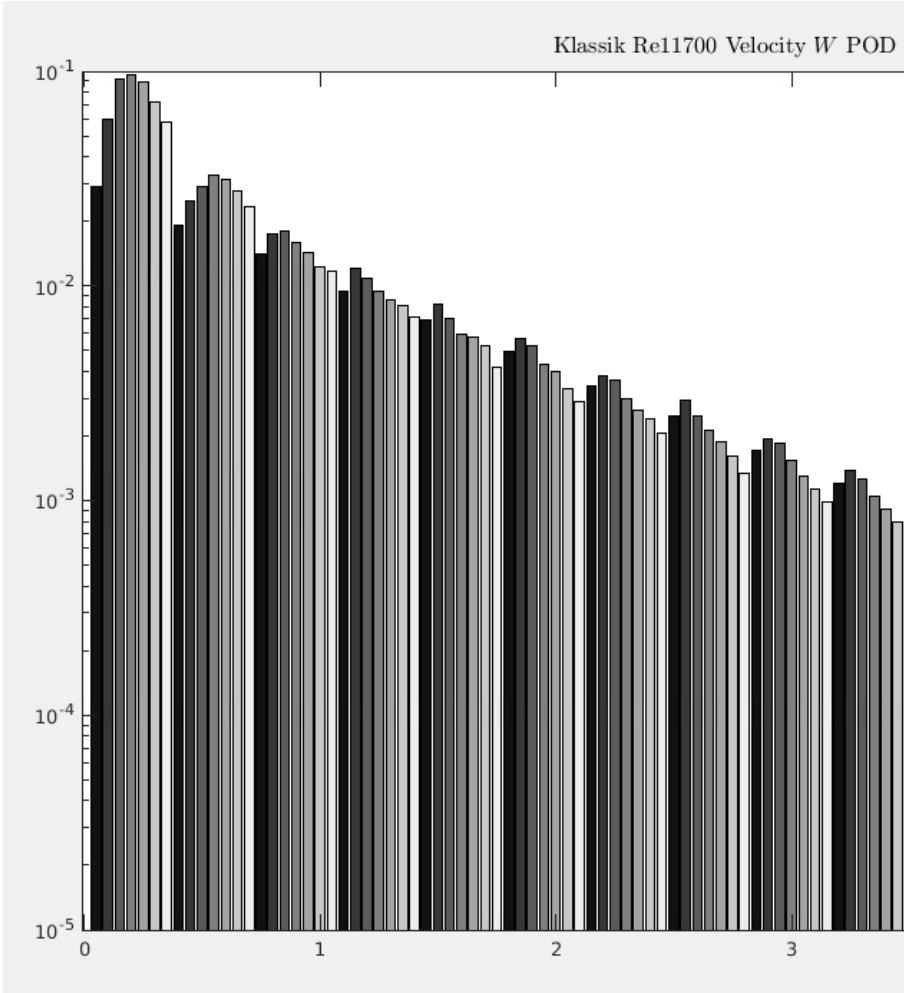
4.4. Klassik



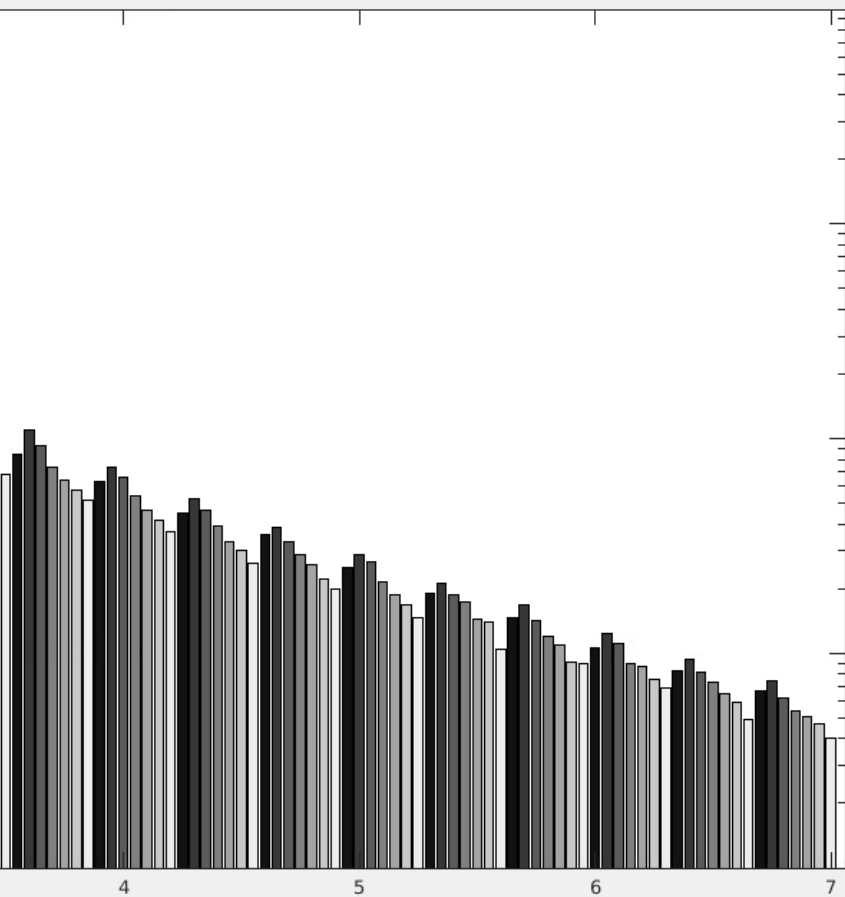
POD S=3.0

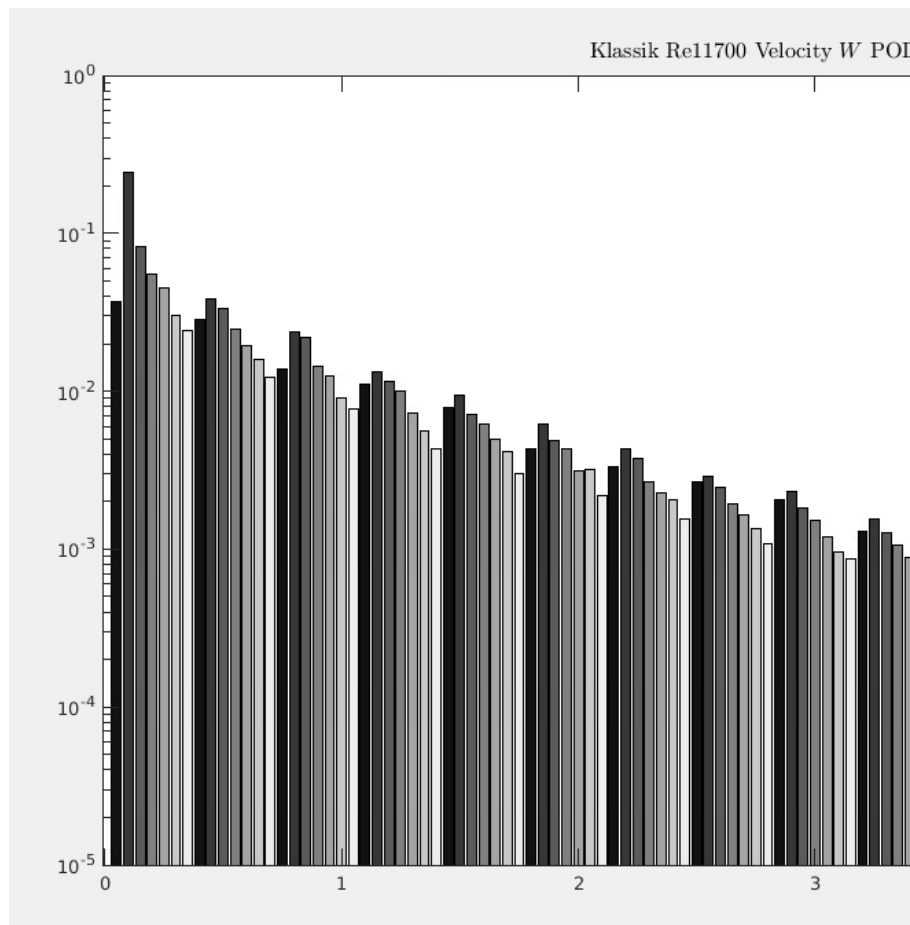
or Rotation Number  $N = 3.0$



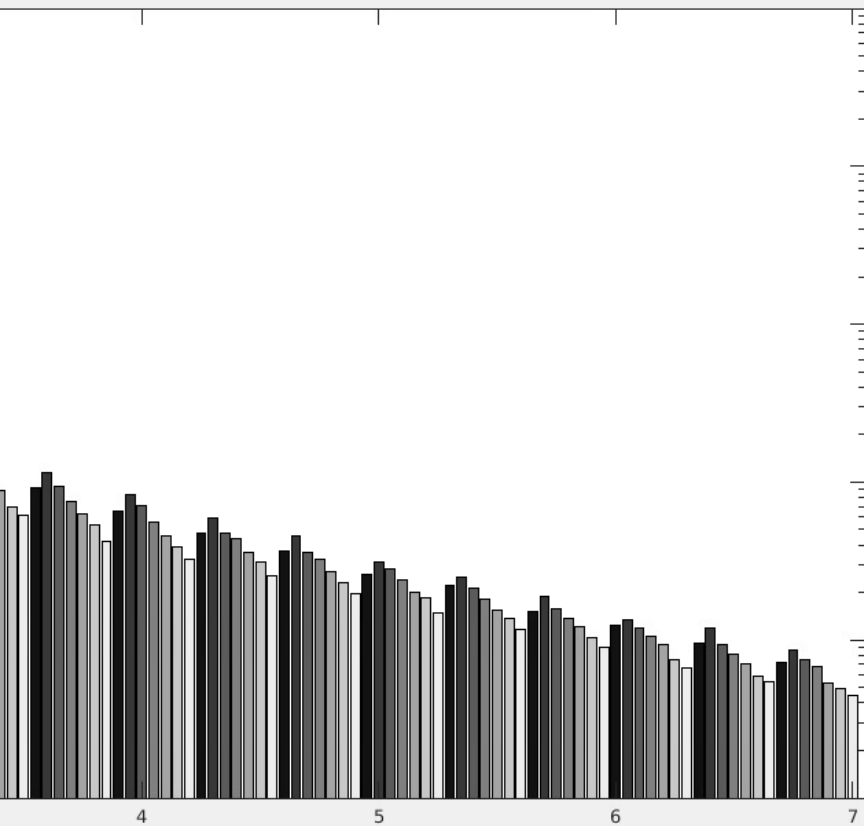


## n=0 Classic

for Rotation Number  $N = 0.0$ 



D for Rotation Number  $N = 3.0$

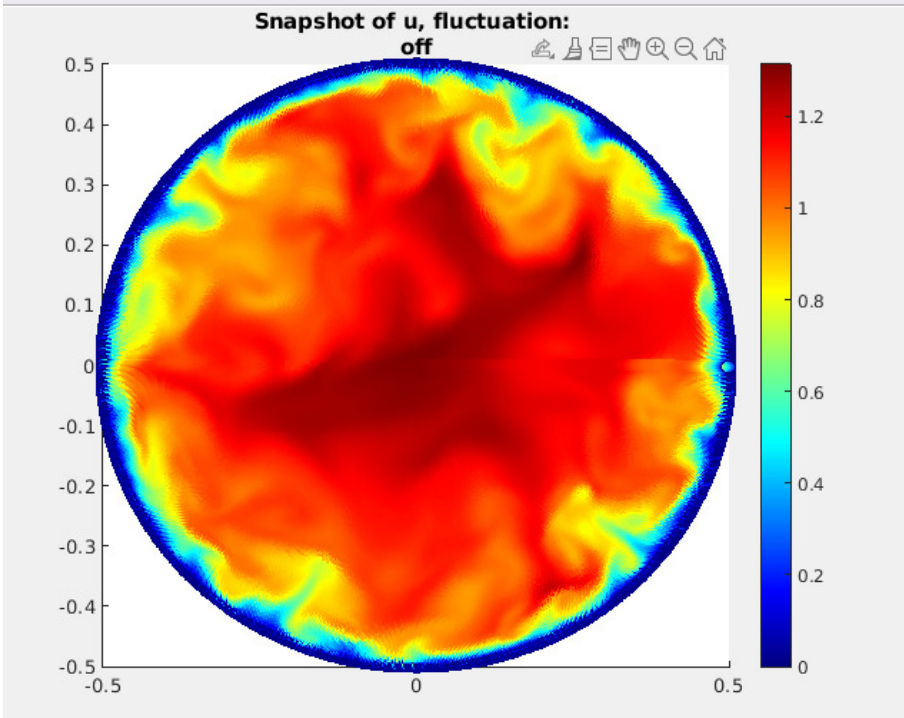




analysis

## 6. Recon

struction



nstruction

**REPOD Reconstruction,  $t=2$  using  $(n,m)=(400,50)$  modes, obf13**

